

Shark-S455ME Embedded Multi-Beam Side Scan Sonar

www.lcsonar.com



The Shark-S455M Embedded Multi-beam Side Scan Sonar is specifically designed for USVs (Unmanned Surface Vehicles), ROVs (Remotely Operated Vehicles), AUVs (Autonomous Underwater Vehicles), UUVs (Unmanned Underwater Vehicles), and other embedded platforms. The system's towfish incorporates five beams per side, ensuring high-speed operation and high-resolution imaging. It features an advanced dynamic digital focusing algorithm that significantly enhances along-track resolution at mid-range and near-range distances. The ability to scan at high speed greatly improves survey efficiency. Additionally, the system supports a low-speed, dual-frequency scanning mode that can be switched in real time, achieving an optimal combination of high resolution and long-range coverage.

The system consists of two transducer arrays, an electronic unit, and OTech's proprietary sonar software. The electronic unit comes in two versions: a built-in non-sealed type and an external sealed type. Designed for ultra-low power consumption, the system operates on a DC supply of 18 – 36V.

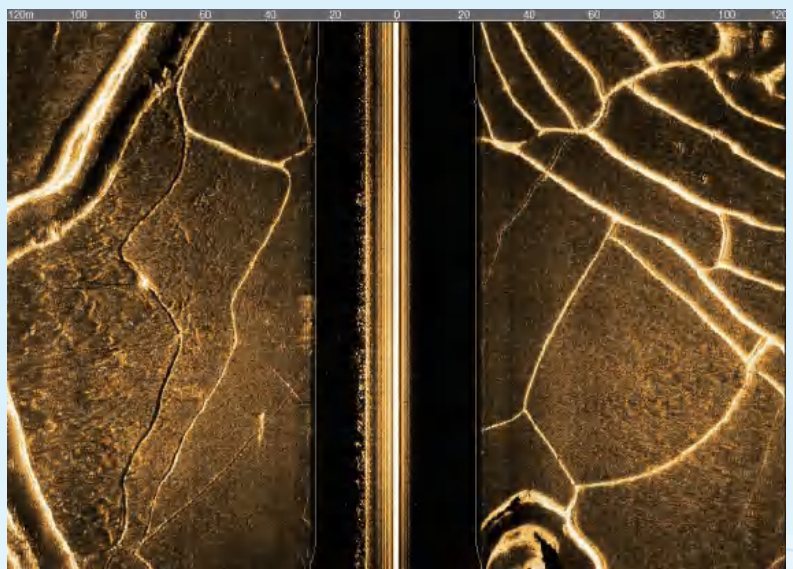
The proprietary OTech software includes features such as real-time image mosaicking, sonar image display, survey line planning and navigation, track tracking and coverage display, data recording and playback, target management and export, and multi-window sensor information display. The sonar image adaptive equalization technology ensures consistent display quality for both near and far images. The software's basic parameters can be controlled remotely. It can output raw data in real time for AI-based automatic target recognition development, while simultaneously saving data in XTF format for processing with third-party software. SDK support is available for secondary development.

Features

- Dynamic digital focusing algorithm, which significantly enhances resolution
- 5 beams per side (10 total), delivering high-resolution imaging at speeds up to 10 knots
- Command-based remote control of operations and parameter settings
- Real-time raw data logging and output for auto target recognition development
- OTech's multifunctional software offers free periodic upgrades and updates.
- Full-coverage real-time mosaicking and imaging with SDK support.

Applications

- Military applications, mine hunting, and small target surveying
- Search and rescue, drowning rescue, and salvage operations
- Marine geology and geophysical exploration and classification
- Archaeological surveys, underwater ancient city and shipwreck searches
- Cable and pipeline laying, as well as route inspection and maintenance
- Seafloor surveying and exploration for offshore wind and other renewable energy projects



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| Sonar Specifications | Shark-S455ME |
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| Number of Beams | 10 beams (5 per side) |
| Operating Frequency | High-speed mode: 450kHz; Low-speed mode: 100 kHz / 450kHz simultaneous |
| Pulse Type | LFM (Chirp) / CW, 60 kHz bandwidth |
| Maximum Range | 450m @ 150kHz; 180m @ 450kHz |
| Beamwidth | Horizontal: 0.56° @ 150kHz; 0.14° @ 450kHz; Vertical: 50° |
| Resolution | Along-track resolution: 450kHz: 15cm @ 60m, 45cm @ 180m; 150kHz: 0.01h (range); Across-track resolution: 450kHz: 1.25cm; 150kHz: 2.5cm |
| Transducer Mounting Angle | Best performance at 20° downward tilt |
| Maximum Operating Depth | 2000m (Customizable up to 6000 meters) |
| Transducer Dimensions / Weight | 1347mm(L)×86mm(W)×23mm(H) / 8kg |
| Sealed Electronic Unit Dimensions / Weight | 500mm(L)×130mm(D) / 9kg |
| Unsealed Electronic Unit Dimensions / Weight | 516mm(L)×174mm(W)×145mm(H) / 9kg |
| Power Supply / Consumption | 18~36VDC, maximum 50W |
| OTech Software | Real-time mosaicking; live online mapping; OTSS and XTF formats recording; SDK development support; continuous raw data output. |
| Interface | High-speed Ethernet communication supporting real-time input of control commands; equipped with RS-422 synchronous interface signals. |
| Operating Speed | High-speed mode: up to 10 knots; Low-speed mode: 2 - 6 knots |

